

# Using a micro-UAV for ultra-high resolution multi-sensor observations of Antarctic moss beds



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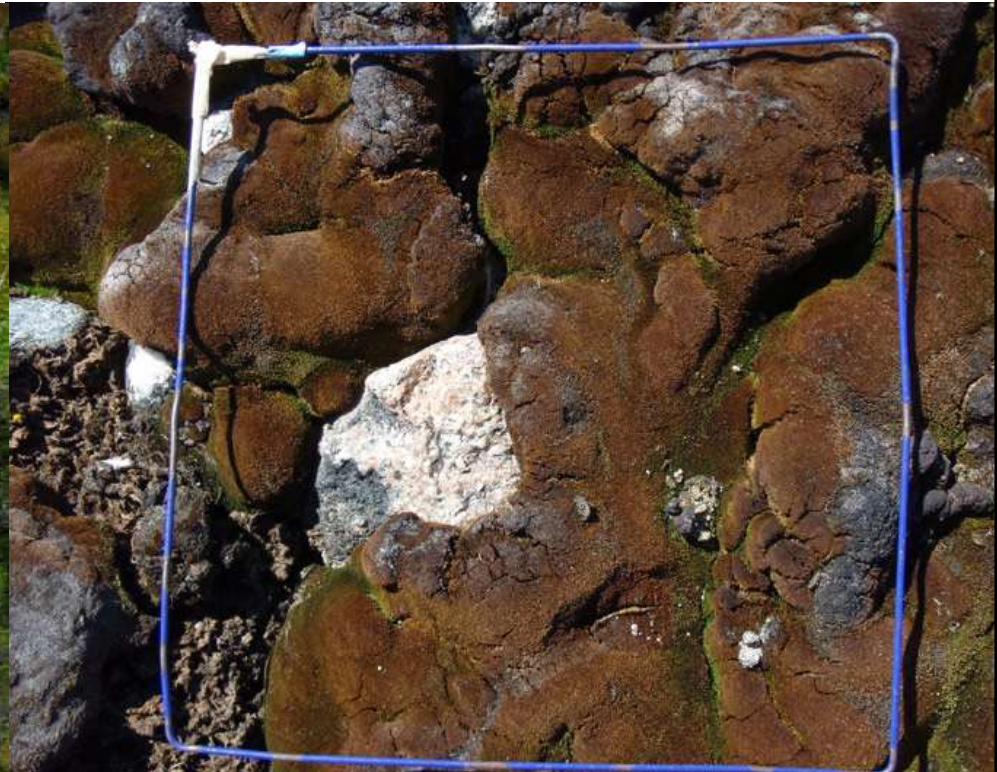




# Life is getting tougher



2003



2008

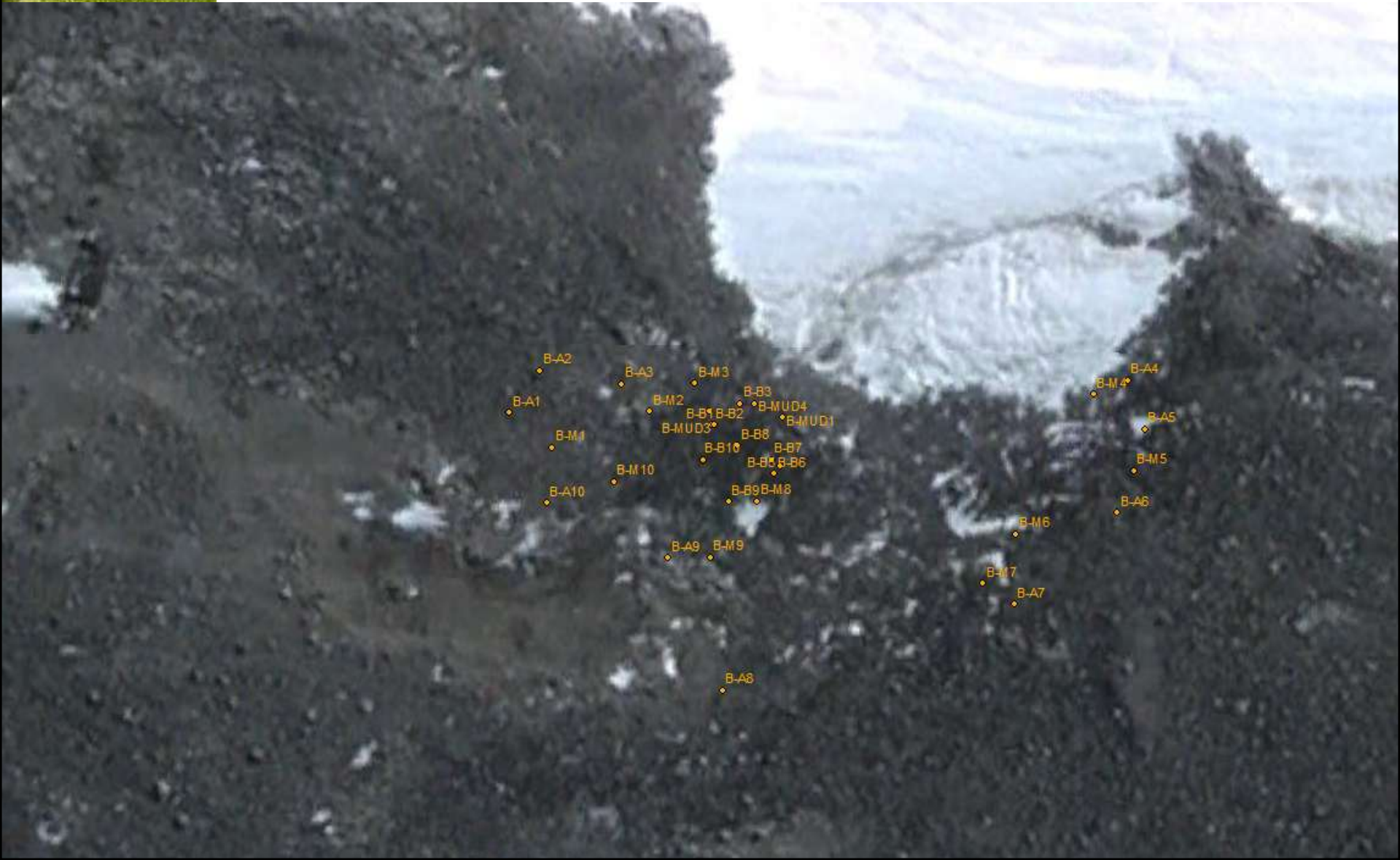
Source: Prof. Sharon Robinson



# QuickBird 2006



# Antarctic Special Protected Area 135





# OktoKopter

IMU, GPS,  
Autopilot

OktoKopter  
multi-rotor  
helicopter

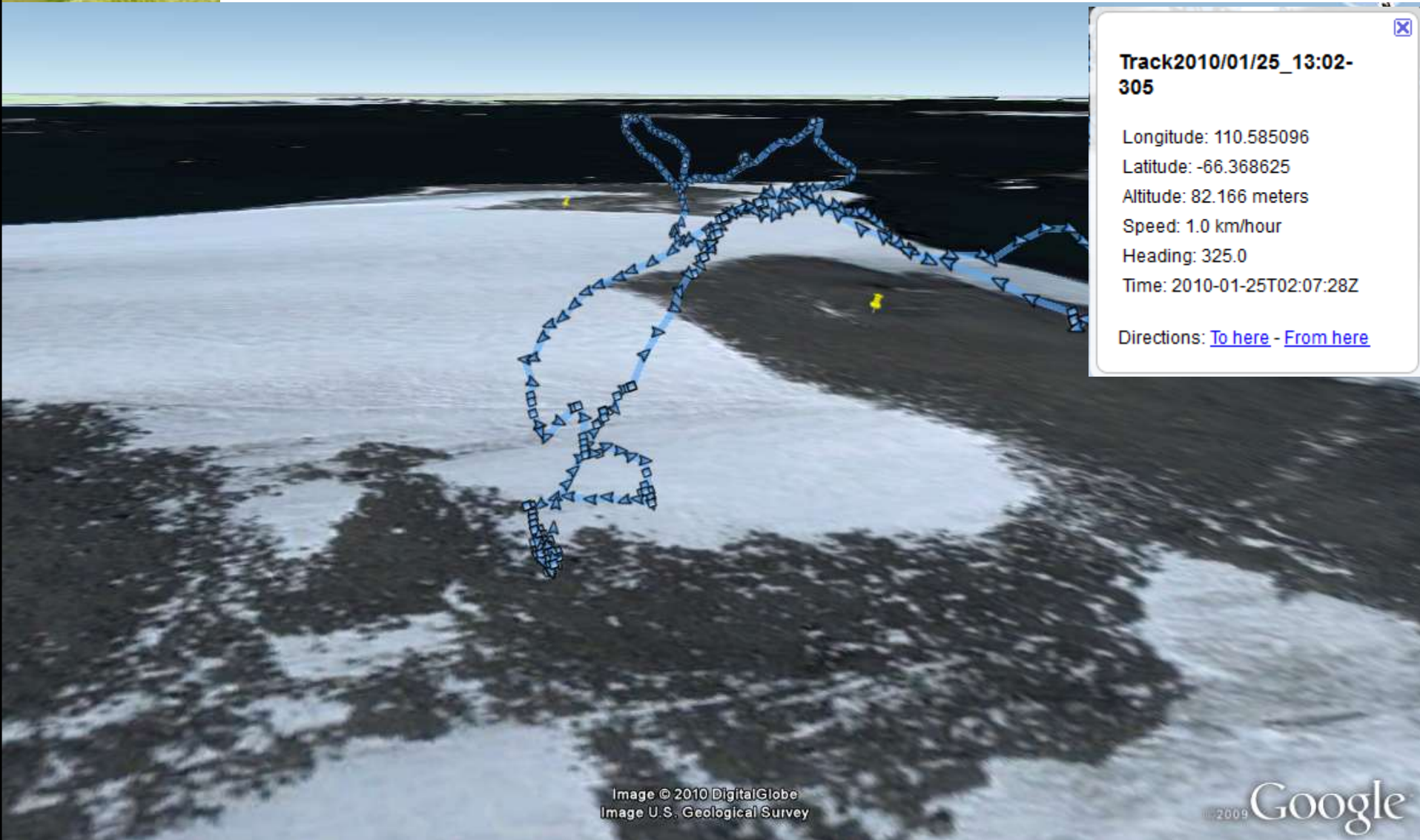
Stabilised  
sensor mount

Digital SLR  
(Canon 550D)

6-band  
multispectral  
sensor



# Flight path in Google Earth





# Objectives

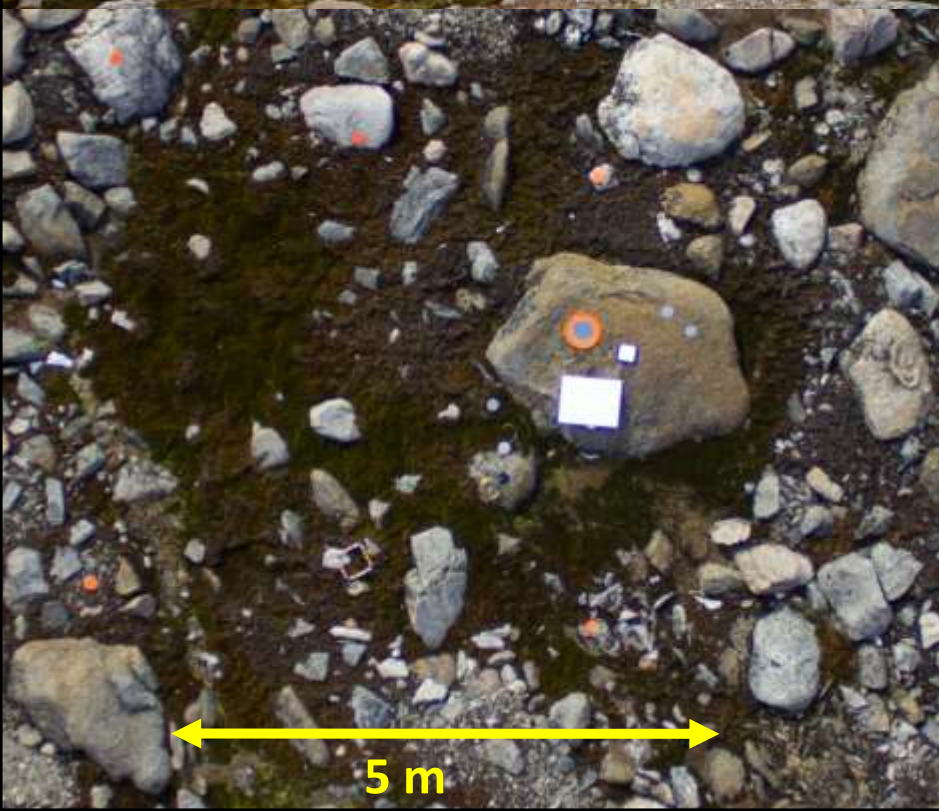
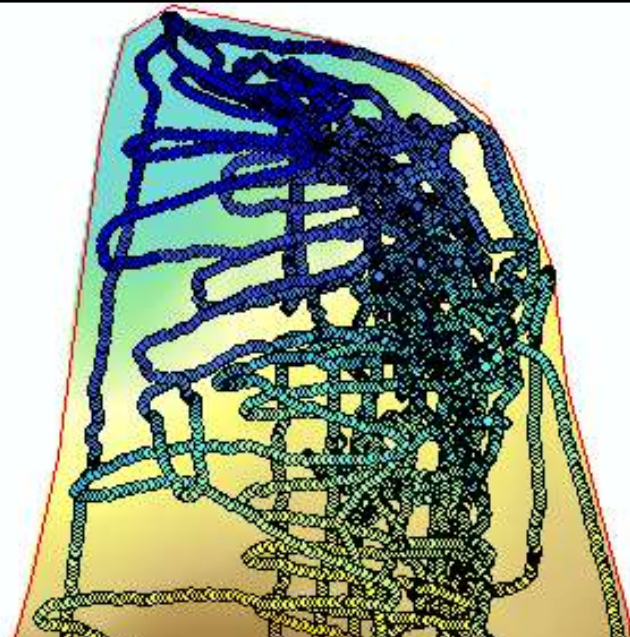
- To map the spatial extent and health of Antarctic moss beds from UAV photography, multispectral, and thermal imagery
- To capture micro-topography of the moss bed environment based on Structure from Motion (SfM) point clouds













# Photo Tourism - Bundler

- Technique: Structure from Motion (SfM)
- Determines location, orientation, and radial distortion of cameras and sparse 3D geometry



Photo Tourism: Exploring image collections in 3D  
Noah Snavely, Steven M. Seitz, Richard Szeliski  
Proceedings of SIGGRAPH 2006







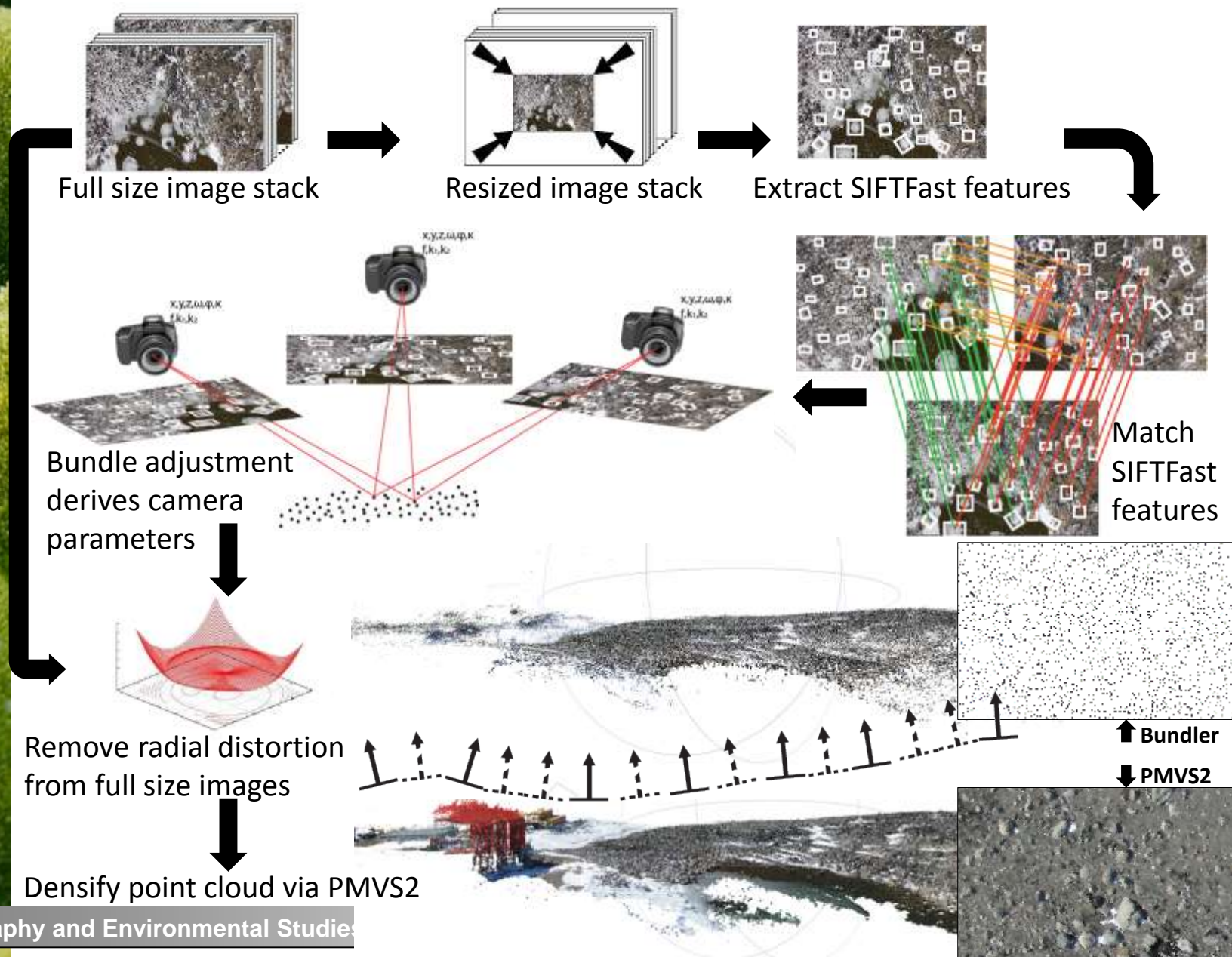
# PMVS2

- Patch-based Multi-View Stereo
- Furukawa, Y., & Ponce, J. (2009). Accurate , Dense , and Robust Multi-View Stereopsis. *IEEE Transactions on Pattern Analysis and Machine Intelligence*.
- Multi-view stereopsis for dense point reconstruction
- Match, expand, filter procedure
- Start with camera positions and sparse point cloud and expand patches
- Filter out false matches





# UAV-MVS Point Cloud Generation





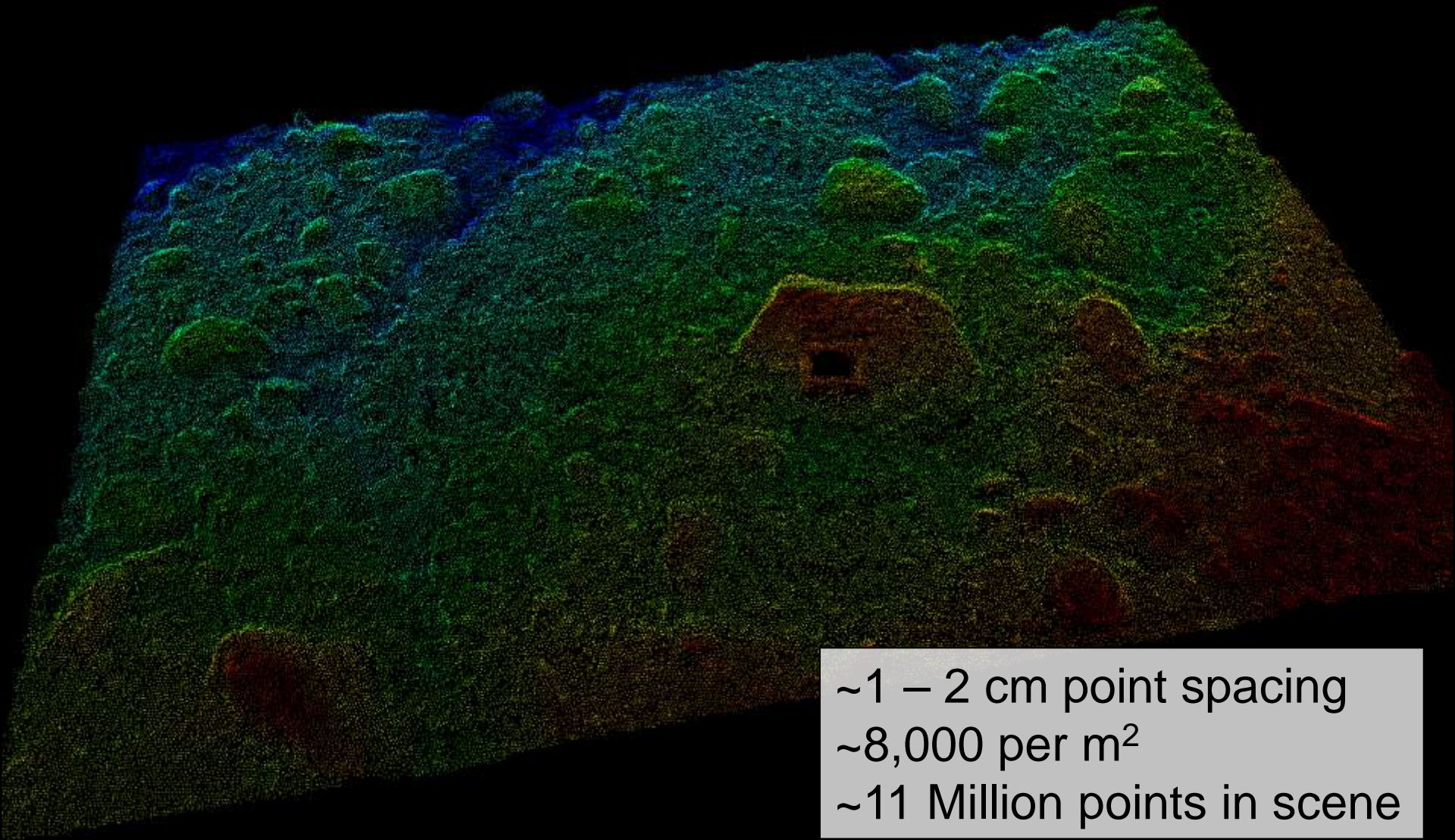
# UAV-MVS point cloud





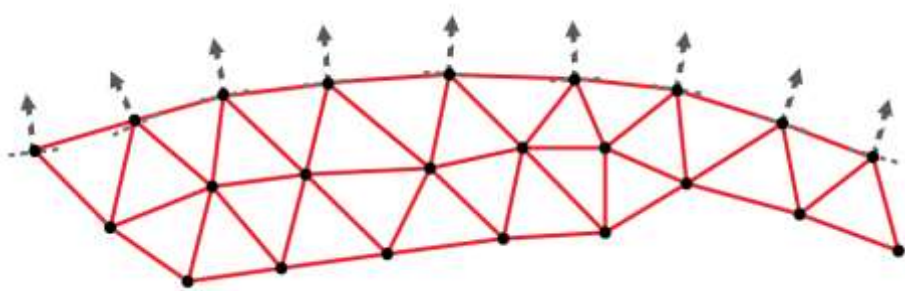


# UAV-MVS point cloud



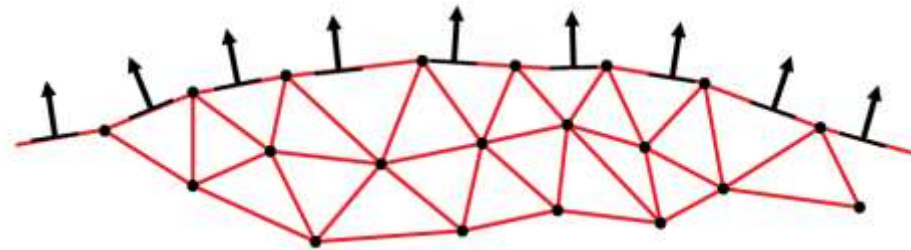


# Terrain surface interpolation

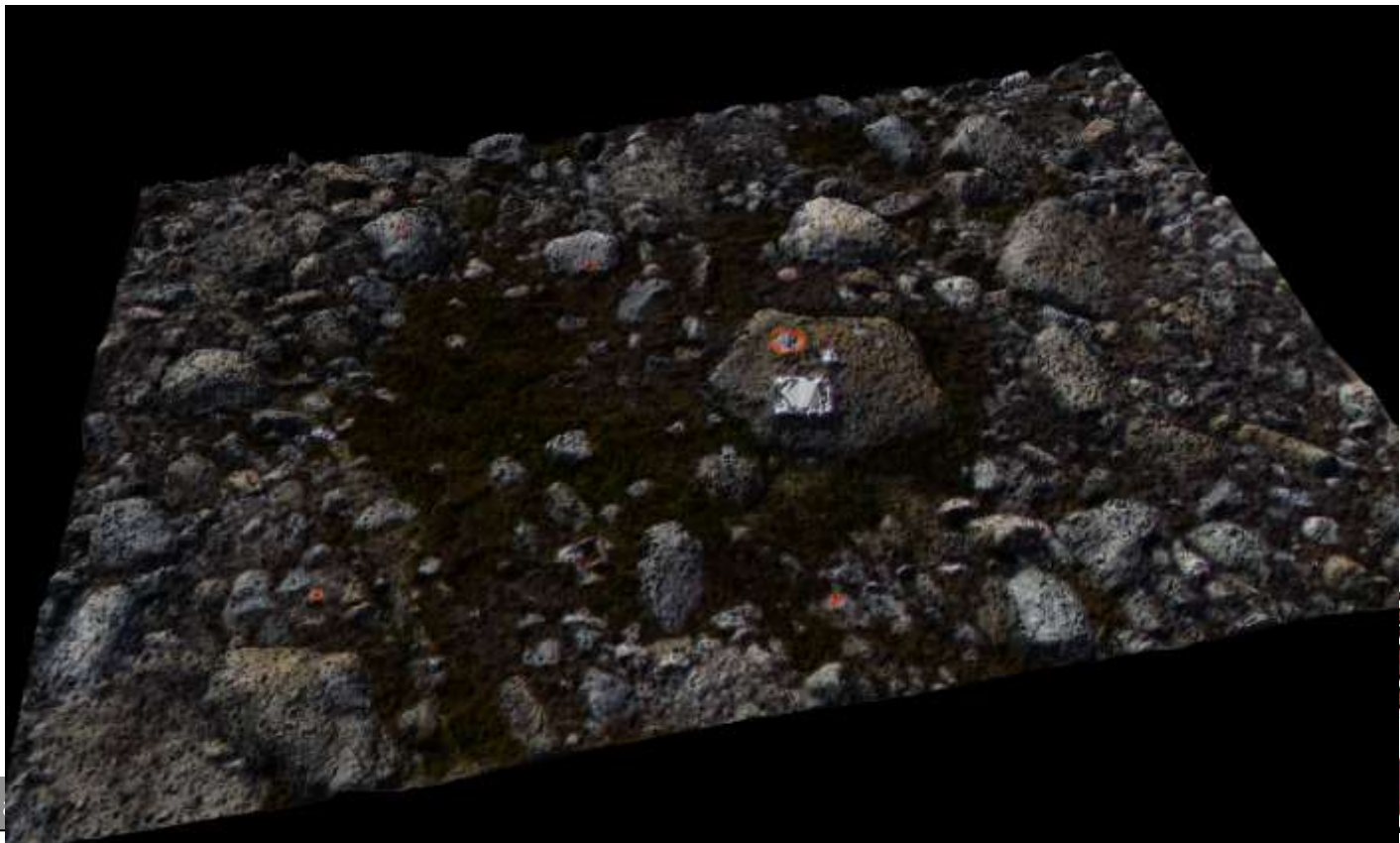


Traditional interpolated TIN

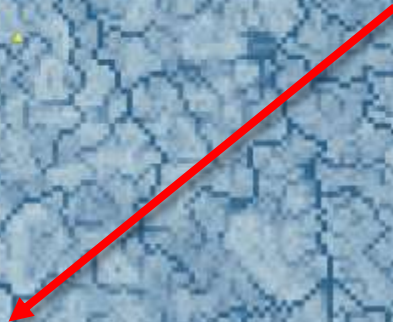
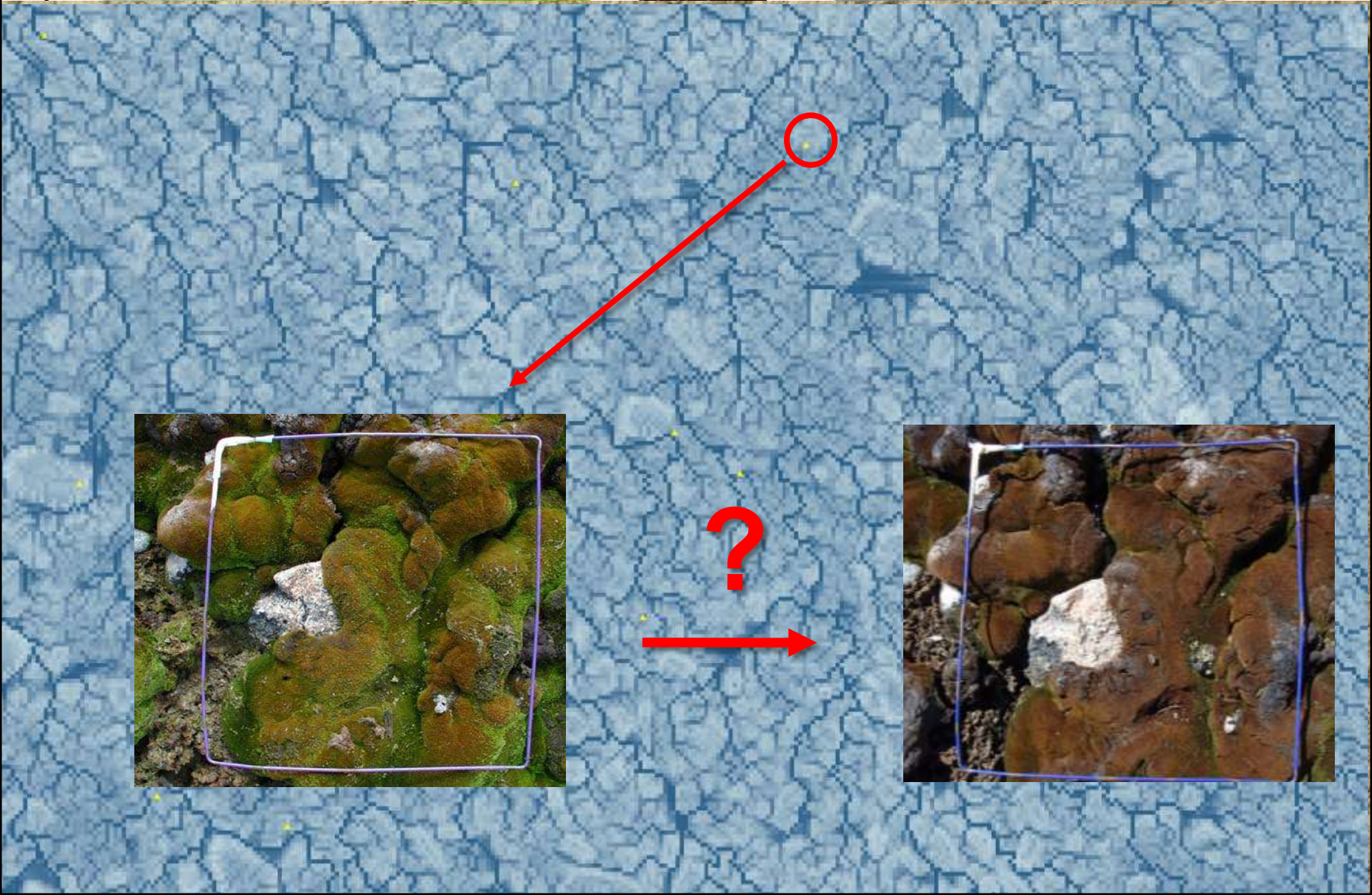
OR



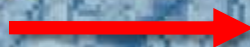
Poisson 3D surface construction  
(Kazhdan *et al.* 2006)





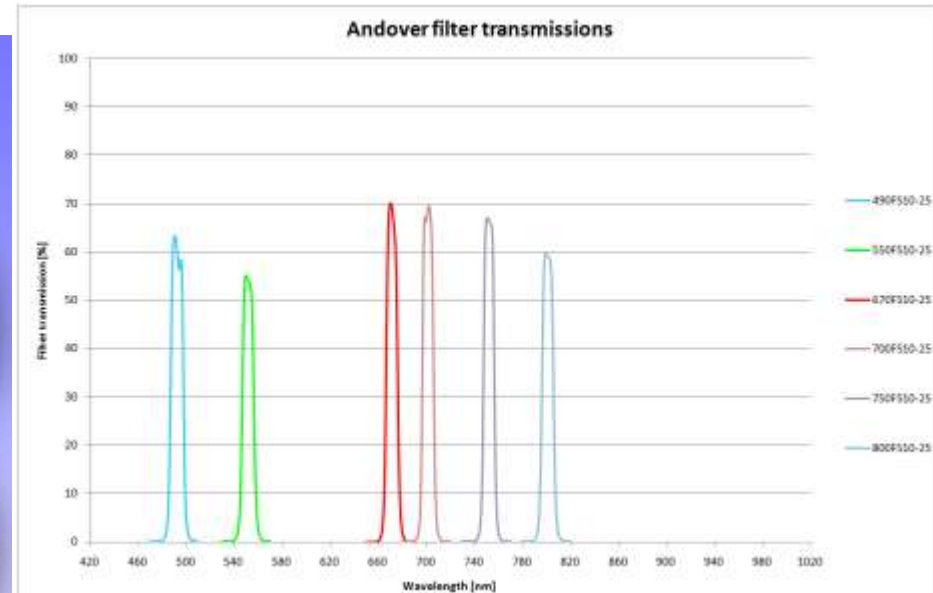


?

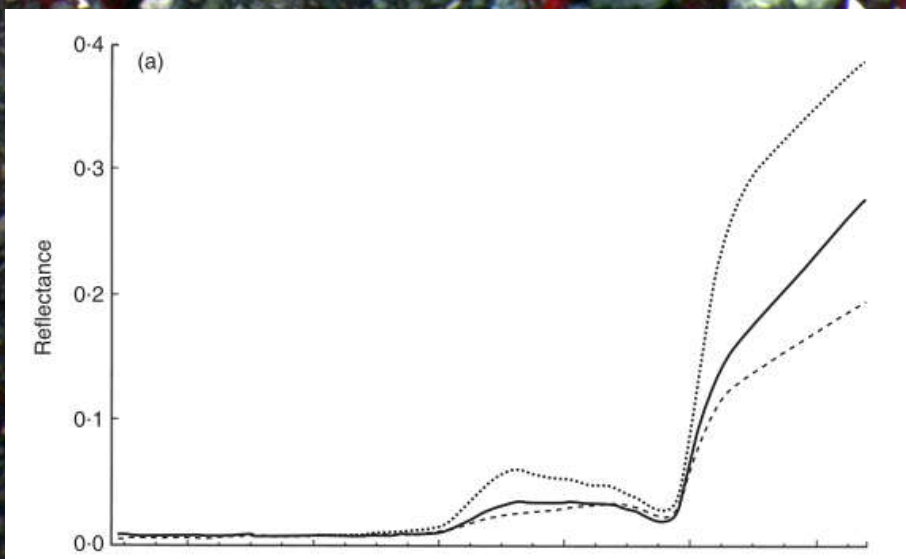
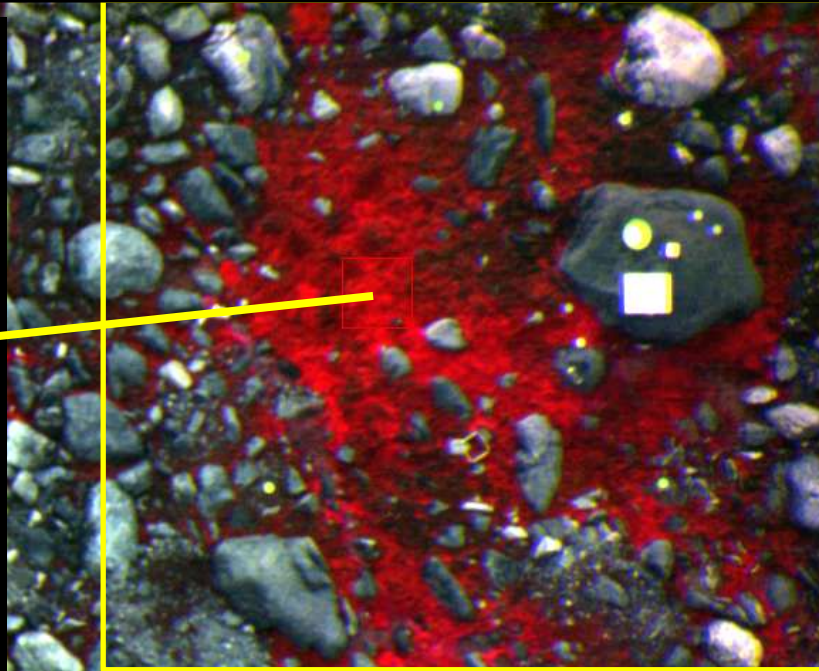
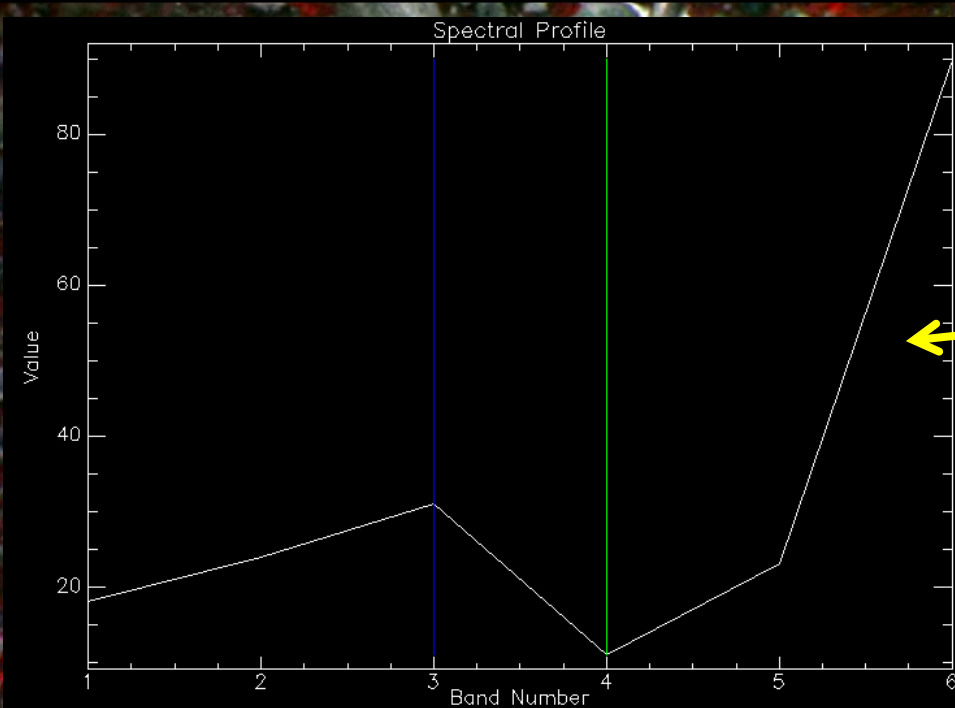




# Multispectral *imaging* sensor 6-bands











16

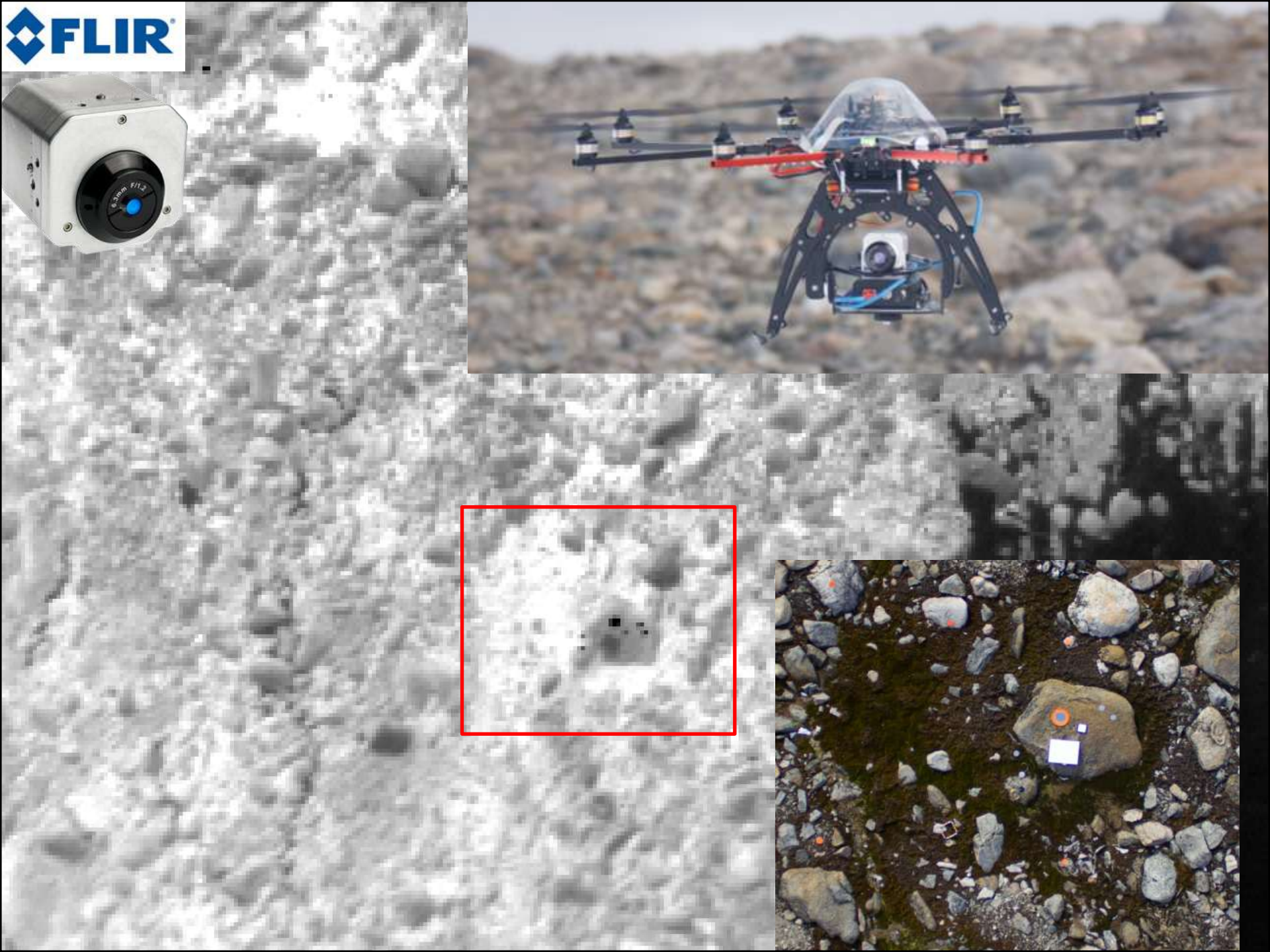
-1

Trefl=-9 Tatm=-9 Dst=2.0 FOV 23

2011-02-24 17:12:38 -10 - +55 e=0.98

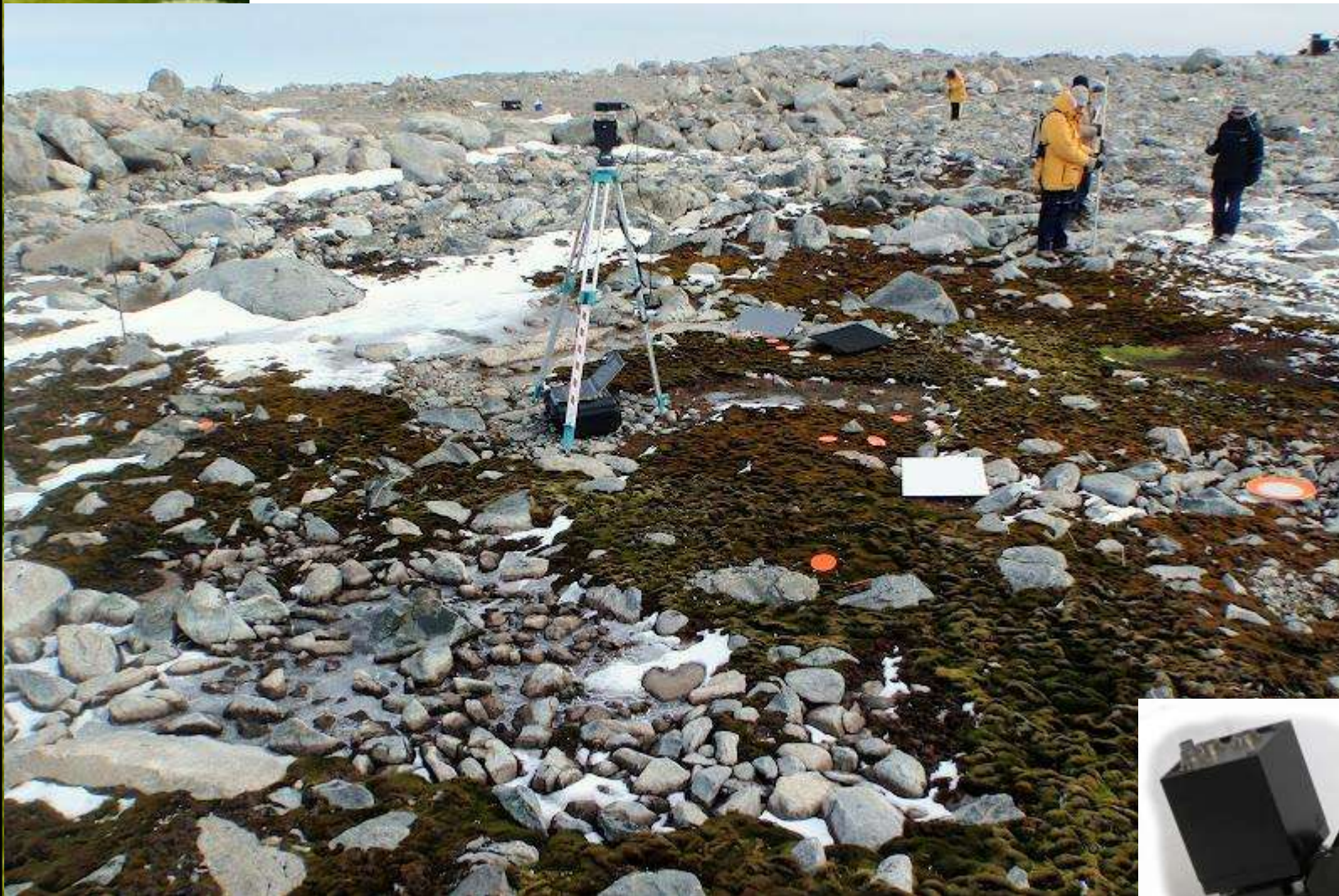
°C







# Hyperspectral field scans



Source: Zbynek Malenovsky

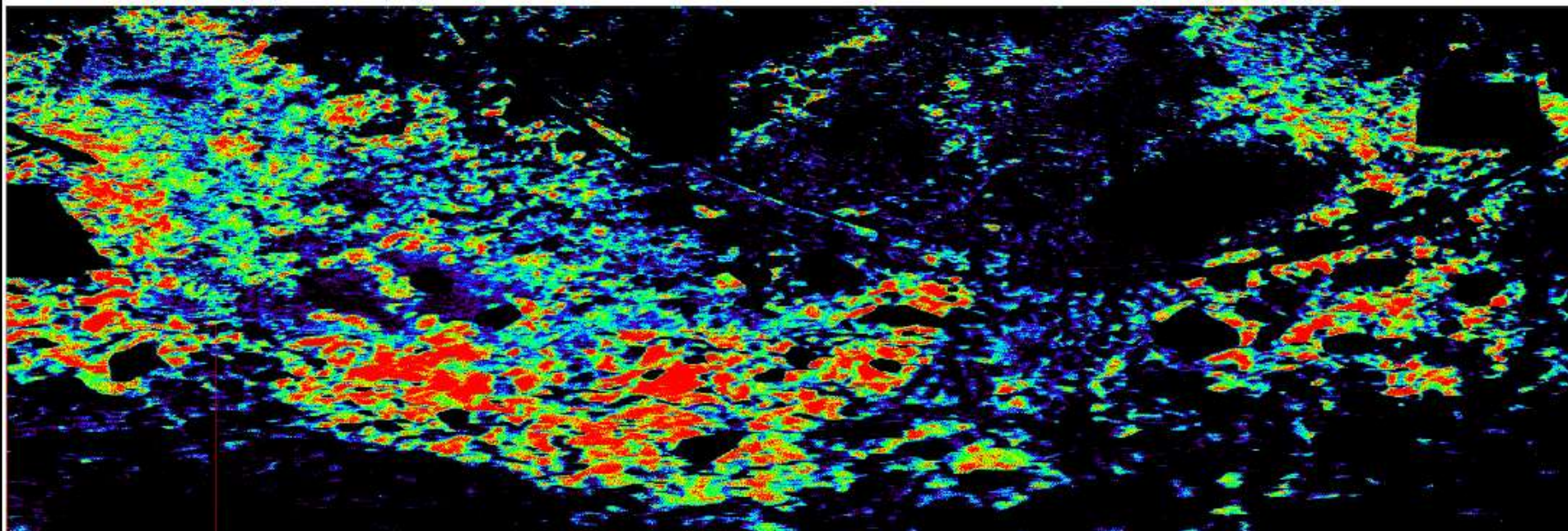




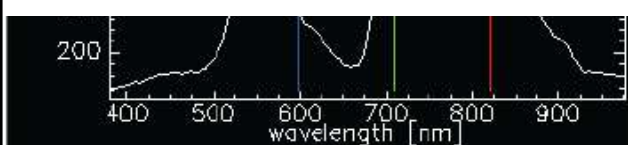
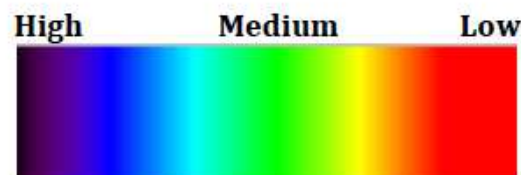
# Hyperspectral field scanning

**HYPERSPECTRAL SCAN OF MOSS-BED AT ASPA 135** (Casey, Antarctica, 29-01-2012, diffuse irradiance ~ full overcast)

Sensor: HyperSpecII (Headwall), spectral binning 2x, integration time 40 ms, gain 3.



Estimated Actual Stress Level:



Spectral signature: **Unstressed moss**

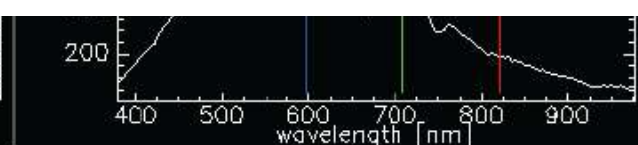
Normalized Difference Veg. Index: **NDVI = 0.45**

(DN ~ Digital Numbers of the reflected light intensity in 12-bit digitalization)



Spectral signature: **Stressed moss**

Normalized Difference Veg. Index: **NDVI = 0.10**

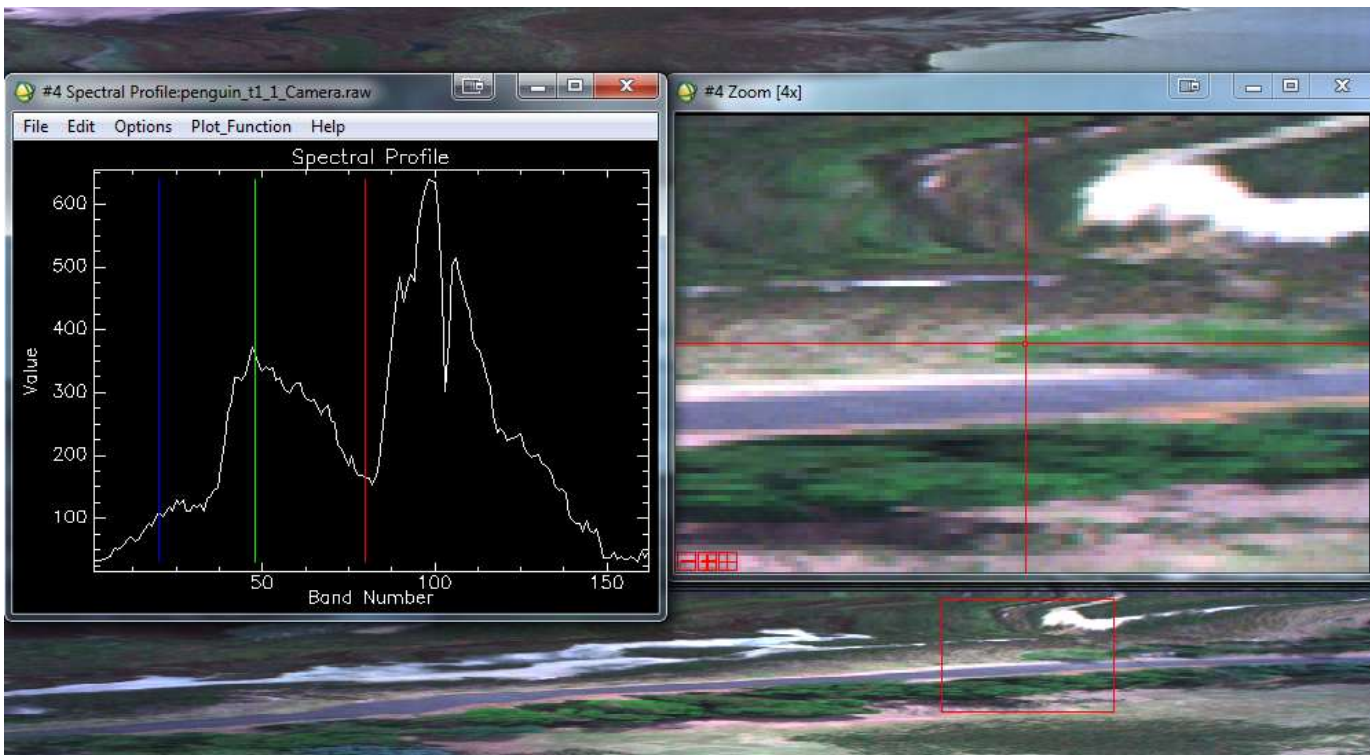


Spectral signature: **Disturbed (dead) moss**

Normalized Difference Veg. Index: **NDVI ~ 0.00**



# Hyperspectral UAV



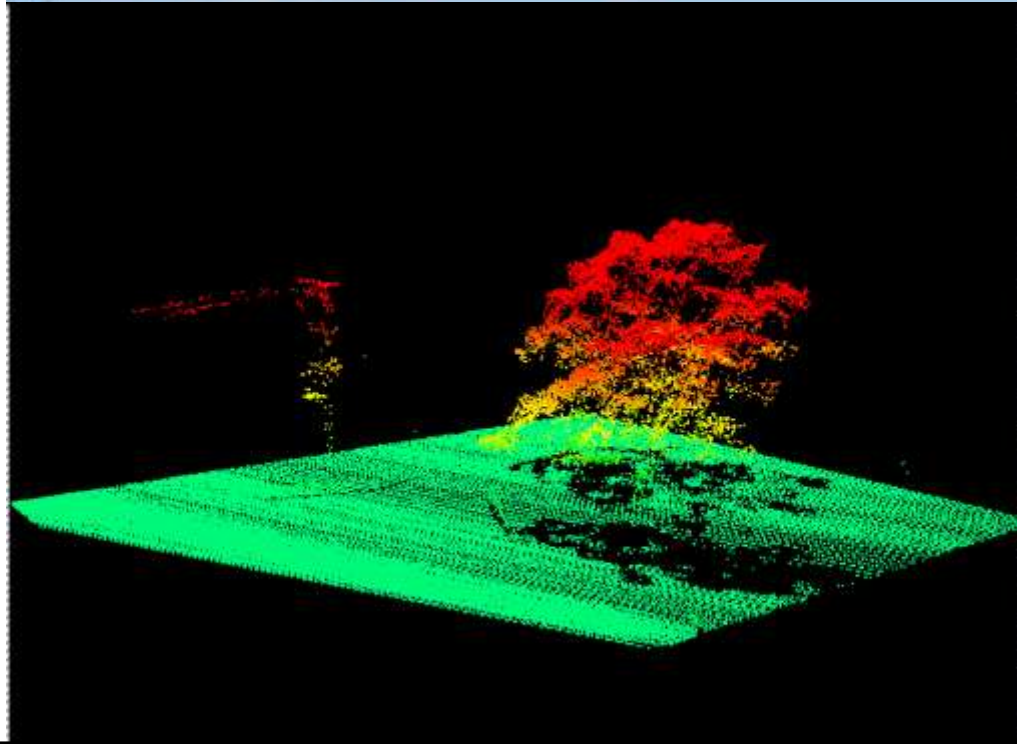


# SkyJib – 5+ kg payload





# LiDAR Okto



TerraLuma



# Conclusions

- UAV is an effective tool to capture the scale niche required for moss bed mapping (and monitoring)
- SfM and multi-view stereo techniques are suitable for dense reconstruction of 3D terrain geometry
- DEM generated from point clouds and DEM derivatives provide important environmental indicators for moss bed health
- Future work will focus on integration of multiple sensors and hyperspectral capabilities





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- School of Geography & Environmental Studies
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